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**MR1972161 (2004b:93025)****[Walker, David M.](#) (5-WA-AD); [Froyland, Gary](#) (5-WA-AD); [Judd, Kevin](#) (5-WA-AD); [Mees, Alistair I.](#) (5-WA-AD)****Controllers for nonlinear systems using normal forms. (English summary)***Internat. J. Bifur. Chaos Appl. Sci. Engrg.* **13** (2003), *no. 2*, 459–465.[93B10](#) ([37D45](#) [37G05](#) [93D15](#))[Journal](#)[Article](#)[Doc  
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**References: 0****Reference Citations: 0****Review Citations: 0**

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Summary: “We describe a method for the design of feedback stabilization control laws for nonlinear systems using the theory of normal forms and results from optimal control theory. We show that the resulting controllers can provide a larger region of stability than local linear controllers designed to perform the same task.”

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