

Old & new co-ordinates

Aim lecture: A wise choice of co-ordinates can make life much easier. We give some examples showing how to make a linear change of co-ords to facilitate calculations.

Suppose we have old co-ords $(x_1, \dots, x_n) \in \mathbb{F}^n$ & some new co-ords $(y_1, \dots, y_n) \in \mathbb{F}^n$. They really lie in different copies of \mathbb{F}^n & we need some notation to distinguish the two.

Notn

We let \mathbb{F}_x^n be a copy of \mathbb{F}^n whose co-ords are (x_1, \dots, x_n) & \mathbb{F}_y^n be another copy of \mathbb{F}^n whose co-ords are (y_1, \dots, y_n) .

We let $GL_n(\mathbb{F})$ denote the set of invertible $n \times n$ -matrices with entries in \mathbb{F} .

Change of co-ordinate matrix

Defn

A *change of co-ordinates matrix* (with say old co-ords (x_1, \dots, x_n) & new co-ords (y_1, \dots, y_n)) is a co-ord system of the form $C : \mathbb{F}_y^n \longrightarrow \mathbb{F}_x^n$. Note the change of co-ordinates formula

$$(x_1, \dots, x_n)^T = C(y_1, \dots, y_n)^T, \quad (y_1, \dots, y_n)^T = C^{-1}(x_1, \dots, x_n)^T$$

Rem The possible change of co-ords matrices correspond to the elements of $GL_n(\mathbb{F})$.

E.g. Best to visualise an example geometrically. Suppose $C : \mathbb{R}_y^2 \longrightarrow \mathbb{R}_x^2$ is given by the matrix

$$C = \begin{pmatrix} \frac{3}{5} & -\frac{4}{5} \\ \frac{4}{5} & \frac{3}{5} \end{pmatrix}$$

Reflections via change of co-ordinate system

E.g. Use change of co-ordinates to find the matrix $A \in M_{22}(\mathbb{R})$ representing reflection about the line $x_2 = \frac{4}{3}x_1$.

A We use the co-ordinate system $C : \mathbb{R}_y^2 \rightarrow \mathbb{R}_x^2$ defined by the matrix

$$C = \begin{pmatrix} \frac{3}{5} & -\frac{4}{5} \\ \frac{4}{5} & \frac{3}{5} \end{pmatrix}.$$

In the new co-ords, the representing matrix is easy

$$\begin{pmatrix} y_1 \\ y_2 \end{pmatrix} \mapsto \begin{pmatrix} y_1 \\ -y_2 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}.$$

But our theory of matrix reprns also gives

$$C^{-1}AC = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

Note

$$C^{-1}AC : \mathbb{R}_y^2 \xrightarrow{C} \mathbb{R}_x^2 \xrightarrow{A} \mathbb{R}_x^2 \xrightarrow{C^{-1}} \mathbb{R}_y^2.$$

Hence $A =$

Linear maps & change of co-ords

The previous example illustrates the general principle below.

Prop

Let \mathbb{F}_x^n be the space of old co-ords (x_1, \dots, x_n) & \mathbb{F}_y^n be the space of new co-ords (y_1, \dots, y_n) which are related by the change of co-ords matrix $C : \mathbb{F}_y^n \rightarrow \mathbb{F}_x^n$. If $A_x : \mathbb{F}_x^n \rightarrow \mathbb{F}_x^n$ denotes a linear map in old co-ords & $A_y : \mathbb{F}_y^n \rightarrow \mathbb{F}_y^n$ denotes the corresponding map in new co-ords then

$$A_y = C^{-1}A_xC, \quad A_x = CA_yC^{-1}$$

Rem It is useful to think of the composite

$$CA_yC^{-1} : \mathbb{F}_x^n \xrightarrow{C^{-1}} \mathbb{F}_y^n \xrightarrow{A_y} \mathbb{F}_y^n \xrightarrow{C} \mathbb{F}_x^n$$

as the sequence

- 1st pass to new co-ords with C^{-1}
- then use linear transformation A_y wrt new & easier co-ords (y_1, \dots, y_n) .
- finally use C to convert back to original co-ords.

Rotations via change of co-ords

E.g. Write down the matrix representing rotation about the axis $\mathbb{R}\mathbf{v}$ where $\mathbf{v} = \frac{1}{3}(1, 2, 2)^T$. Suppose the angle of rotation is θ & the direction is given by the right hand rule with thumb pointing in dirn \mathbf{v} .

A We first find a good co-ord system to use.

Rotation example cont'd

Note that the representing matrix in the new co-ords is

Swapping between two co-ordinate systems

Let $C_x : \mathbb{F}_x^n \rightarrow V$, $C_y : \mathbb{F}_y^n \rightarrow V$ be two co-ordinate systems. Then we can pass from x -co-ords to y -co-ords via $\mathbb{F}_x^n \xrightarrow{C_x} V \xrightarrow{C_y^{-1}} \mathbb{F}_y^n$. This suggests

Defn

The *change of co-ordinates matrix* is $C = C_y^{-1} \circ C_x$. Given the x -co-ords \mathbf{x} of a vector $\mathbf{v} \in V$, its y -co-ords are $\mathbf{y} = C\mathbf{x}$.

E.g. Suppose we have new co-ord systems on \mathbb{R}^2 given by

$$C_x = \begin{pmatrix} 2 & 1 \\ 3 & 1 \end{pmatrix}, C_y = \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix}.$$

If the x -co-ords of $\mathbf{v} \in \mathbb{R}^2$ are $\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$, what are the y -co-ords? What is the change of co-ords matrix?

Being careful with identifying vector spaces

Isomorphisms sometimes allow us to identify two vector spaces, but this can be confusing at times, & we should be more careful as follows. Suppose given isomorphisms $\Phi_V : V' \rightarrow V, \Phi_W : W' \rightarrow W$.

Defn

Given isomorphisms Φ_V, Φ_W above, the linear map $T : V \rightarrow W$ induces a *corresponding linear map* $T' = \Phi_W^{-1} \circ T \circ \Phi_V : V' \rightarrow W'$. If there is no confusion in treating Φ_V, Φ_W as identifications, then we may also make the identification $T' = T$.

E.g. Suppose $m = m_1 + \dots + m_M, n = n_1 + \dots + n_N$ so there are natural isomorphisms $\Phi_W : \mathbb{F}^m \rightarrow \mathbb{F}^{m_1} \oplus \dots \oplus \mathbb{F}^{m_M}, \Phi_V : \mathbb{F}^n \rightarrow \mathbb{F}^{n_1} \oplus \dots \oplus \mathbb{F}^{n_N}$ given by “removing” internal parentheses.

Given an $M \times N$ -matrix of matrices defining a linear map $T : \mathbb{F}^{n_1} \oplus \dots \oplus \mathbb{F}^{n_N} \rightarrow \mathbb{F}^{m_1} \oplus \dots \oplus \mathbb{F}^{m_M}$, the corresponding linear map $\Phi_W^{-1} \circ T \circ \Phi_V : \mathbb{F}^n \rightarrow \mathbb{F}^m$ is just the big matrix obtained by “removing” internal parentheses.