

## Lecture 8: Basis and Dimension

### More Examples of Bases

From thm lecture 6 we know

**Thm 1** Let  $V =$  vector space/ field  $\mathbb{F}$ .

$B = \{\mathbf{v}_1, \dots, \mathbf{v}_n\}$  is a basis iff every  $\mathbf{v} \in V$  is uniquely

**E.g. 1**  $V = M_{mn}(\mathbb{F})$ . For  $i \in$

define  $E_{ij} =$

i.e. 0 everywhere but

$B = \{E_{ij}\}$  is a basis. e.g. for  $M_{22}$  we can uniquely express

**E.g. 2**  $W =$  line through origin in dirn  $\mathbf{w} \in \mathbb{R}^3$ .

**E.g. 3**  $W =$  plane through origin

**Questions** 1. In the  $\mathbb{R}^m$  examples, looks like the number of elements in a basis correspond to the dimension of a subspace. Can use this as a defn

2. Does any vector space have a basis and if so

**Aim lectures 8/9:** Answer 1 in affirmative and provide effective answer for 2.

More precise answer to 1 suggested by

**E.g. 3 revisited**  $W =$  plane through origin

cont'd

More generally have

**Thm 2** Let  $V =$  vector space/ field  $\mathbb{F}$

Let  $S = \{\mathbf{w}_1, \dots, \mathbf{w}_n\}$

Let  $I = \{\mathbf{v}_1, \dots, \mathbf{v}_m\}$

Then

Proof: Omitted. See §6.7.2 of notes. See e.g. 4 below for basic idea of proof.

**Thm 3 - Defn** Let  $V =$  vector space/ field  $\mathbb{F}$

Suppose  $B_1 = \{\mathbf{v}_1, \dots, \mathbf{v}_m\}$  and  $B_2 = \{\mathbf{w}_1, \dots, \mathbf{w}_n\}$  are bases for  $V$ . Then

In this case, say  $V$

&  $\dim V :=$

When no such basis exists,

Proof: By thm 1

$B_1$  spans  $V$  &  $B_2$  lin indep  $\implies$

so  $m = n$ .

**E.g. 4** We have a standard basis  $\{$

so  $\dim \mathbb{R}^n =$

Thm 3  $\implies$  any basis of  $\mathbb{R}^n$

We'll prove this without using thms 2 or 3.

Proof: Let  $B = \{\mathbf{v}_1, \dots, \mathbf{v}_m\}$  be

&  $A =$  so  $A$  is  $n \times m$

We wish to show  $m =$

$B$  lin indep  $\implies A\mathbf{x} = \mathbf{0}$  has

Gaussian elim  $\implies$

(otherwise there are more

$B$  spans so  $A\mathbf{x} = \mathbf{b}$  always

This suggests

Proof is a little delicate. Consider solns  $\mathbf{x}_i$

to  $A \mathbf{x}_i = \mathbf{e}_i$ . Let  $X$  be  $m \times n$ -matrix

$$AX = (A \mathbf{x}_1$$

If  $m < n$  then above argument  $\implies$  there's  
a non-zero soln  $\mathbf{w}$  to  $X \mathbf{w} =$

$$\text{But } \mathbf{w} = I \mathbf{w} =$$

Contradiction  $\implies$

This proves thm 3 in this e.g.

### **E.g. 5**

$$\dim M_{mn}(\mathbb{F})$$

$$\dim \mathbb{P}_k$$

**Corollary 1** For  $V =$  vector space/ field  
 $\mathbb{F}$  of dim  $d$

a) Any lin indep

b) Any spanning set

**E.g. 6** Can't span  $\mathbb{R}^3$  with  $< 3$  vectors  
and any 4 vectors in  $\mathbb{R}^3$  are lin dependent.

We need a lemma on extending lin indep sets

**Lemma** Let  $V =$  vector space/ field  $\mathbb{F}$

Let  $I$  be a lin indep set. If  $\mathbf{v} \in V -$

then  $I \cup$

Geom clear as in

Proof lemma: Consider a lin reln

$\lambda \mathbf{v} +$



If  $\lambda \neq 0$  then solving

Hence,

$I$  lin indep  $\implies$

Hence

**Corollary 2** Let  $V =$  vector space/ field  $\mathbb{F}$ .

Let  $B = \{\mathbf{v}_1, \dots, \mathbf{v}_n\} \subset V$ . The following conditions on  $B$  are equivalent:

- a)  $B$  is a basis
- b)  $B$  is lin indep &
- c)

Proof: a)  $\implies$  b) and c) by

Check b)  $\implies$  a): Suppose a) false so  $B$  doesn't span.

Pick  $\mathbf{v} \in$

Lemma  $\implies \{\mathbf{v}, \mathbf{v}_1, \dots, \mathbf{v}_n\}$  is

This contradicts Cor 1a) so a) must hold.

Check c)  $\implies$  a): Suppose a) false so

Say  $\mathbf{v}_1 \in$

**E.g. 7** Let  $B = \{\mathbf{v}_1, \dots, \mathbf{v}_n\}$  be an o/n set of vectors in  $\mathbb{R}^n$ .

**Remark** Concept of basis for infinite di-

mensional vector spaces is not as useful. In particular, the defn of span of an infinite set is usually modified.