

Lecture 16: Algebra of linear transformations

Aim Lecture See how the algebra of linear maps mimics the algebra

Linear structure

Defn 1 Let $T, T' : V \longrightarrow W$ be

Let $\lambda, \mu \in \mathbb{F}$. Define new maps

Sum: $T + T' : V \longrightarrow W$ by

scalar multiple: $\lambda T : V \longrightarrow W$ by

Linear Comb: $\lambda T + \mu T' : V \longrightarrow W$ by

Propn 1 $T + T', \lambda T$ are linear too. Hence so is $\lambda T + \mu T'$.

Proof: Check λT lin: for $\mathbf{v}, \mathbf{w} \in V, \alpha \in \mathbb{F}$

Add Cond'n: $(\lambda T)(\mathbf{v} + \mathbf{w}) \stackrel{\text{def}}{=}$

$$= \lambda(T \mathbf{v} +$$

$$= \lambda(T \mathbf{v})$$

$=$

so addn condn holds.

Scalar Multn Cond'n: $(\lambda T)(\alpha \mathbf{v}) =$

So scalar multn condn also holds &

Check $T + T'$ linear: Can prove as above.

Here we only prove in case $V = \mathbb{F}^n, W =$

\mathbb{F}^m so by matrix representation thm there are

$A, B \in M_{mn}(\mathbb{F})$ with

$$(T + T') \mathbf{v} =$$

$T + T'$ is matrix

Proof gives

Formula 1 $T_A + T_B = T_{A+B}$

Sim $\lambda T_A = T_{\lambda A}$.

Fact: Let V, W be vect spaces / \mathbb{F} &

$\text{Hom}_{\mathbb{F}}(V, W)$ be the set of

Then sum & scalar multiple above are an
addn law &

making $\text{Hom}_{\mathbb{F}}(V, W)$ a

No Proof: But note the matrix reprn thm
means $\text{Hom}_{\mathbb{F}}(\mathbb{F}^n, \mathbb{F}^m)$ is essentially

Application to orthogonal projections

e.g. 1 Identity linear map

For vect space V , let $\text{id} : V \longrightarrow V$ be the function $\text{id } \mathbf{v} = \mathbf{v}$. It is linear (CHECK!).

$\text{id} : \mathbb{F}^n \longrightarrow \mathbb{F}^n$ is represented by

since $\text{id } \mathbf{v} = \mathbf{v} =$

e.g. 2 Let $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3 \in \mathbb{R}^3$ be an o/n

Let $P_i := \text{proj}_{\mathbf{v}_i}$

What's $P_{12} := \text{proj}_{\text{span}\{\mathbf{v}_1, \mathbf{v}_2\}}$ onto

Method 1: $P_{12} \mathbf{v} = \text{id } \mathbf{v} -$

$\therefore P_{12} = \text{id}$

so is linear being

Method 2: also $P_{12} \mathbf{v} =$

$\therefore P_{12}$ is matrix multn by

$I_3 -$

Composing linear maps

Propn 2 Let $T : V \longrightarrow W, S : U \longrightarrow V$
be linear maps. Then $T \circ S :$

Proof: ex in checking axioms. Here do case
 $U = \mathbb{F}^n, V = \mathbb{F}^m, W = \mathbb{F}^l$. Matrix rep thm
 \implies

For some $A \in$

For some $B \in$

$$(T \circ S) \mathbf{v} =$$

Formula 2

Example of rotations

Let $T_\theta : \mathbb{R}^2 \longrightarrow \mathbb{R}^2$ be anti-clockwise

What's $T\left(\begin{smallmatrix} x \\ y \end{smallmatrix}\right)$?

Use complex numbers.

$$e^{i\theta}(x + iy) =$$

$$\therefore T \begin{pmatrix} x \\ y \end{pmatrix} =$$

Hence $T_\theta = T_{R_\theta}$ is linear. R_θ is

e.g. 3 Let's verify directly formula 2 for composing T_θ & T_ϕ .

Geom considerations $\implies T_\theta \circ$

$$R_\theta R_\phi =$$

=

$$\text{So } T_{R_\theta R_\phi} =$$

Invertible linear maps

Recall following defns from calculus regarding a function $f : X \longrightarrow Y$.

Defn 2 1) We say that f is one-to-one (1-1) or injective if for any $y \in Y$, the soln

i.e. $f(x) = f(x')$

2) $f : X \longrightarrow Y$ is onto or

i.e. $\text{im } f$

Recall also from calculus

Facts a) A fn $f : X \longrightarrow Y$ is invertible iff f is 1-1 &

b) In this case, the eqn $f(x) = y$ always has

a

denoted $x =$

c) $f \circ f^{-1} =$

e.g. 4 For a basis $B = \{\mathbf{v}_1, \dots, \mathbf{v}_n\}$ of vect space V over \mathbb{F} , $S_B : V \longrightarrow \mathbb{F}^n$ defined by

Why? Given any $\mathbf{y} = (y_1, \dots, y_n)^T \in \mathbb{F}^n$, the unique soln

Propn 3 If $T : V \longrightarrow W$ is linear and invertible then

Proof: in case $T = T_A$ for $A \in M_{mn}(\mathbb{F})$.

Since T is invertible, $T \mathbf{x} = A \mathbf{x} = \mathbf{b}$ always

Hence A is

$$\therefore T^{-1} =$$

Formula 3 T_A

e.g. 5 Geometrically see “inverse” rotation

$$T_{\theta}^{-1} =$$

Corresponds on matrix side to

$$R_{\theta}^{-1} =$$

=

Generalised matrix representation theorem

Finite bases allow us to represent vect spaces by \mathbb{F}^n & lin maps between vector spaces by

Thm (Generalised Matrix Rep Thm)

Let $T : V \longrightarrow W$ be

$B_V = \{\mathbf{v}_1, \dots, \mathbf{v}_n\}$ be an

$B_W = \{\mathbf{w}_1, \dots, \mathbf{w}_m\}$ be an

Let $A = (\mathbf{a}_1 \dots \mathbf{a}_n)$ be

with columns

Then (*) $[T \mathbf{v}]_{B_W} =$

Why? Both sides of (*) are linear in \mathbf{v} since they are composites

\therefore suffice check (*) holds for $\mathbf{v} =$

LHS = $[T \mathbf{v}_i]_{B_W} =$

RHS =

e.g. 6 Rotation matrix via reprn thm

Let $V =$ vect space of geom vectors in 2-dim

Let $T : V \longrightarrow V$ be lin map which rotates

We put coords on V by letting \mathbf{u}_1 be any length

Rotate \mathbf{u}_1 90°

Then $B = \{\mathbf{u}_1,$

Q What matrix R represents

A Trig $\implies T \mathbf{u}_1 =$

so $[T \mathbf{u}_1$

Sim $[T$

$\text{Thm} \implies T$ is

wrt basis

$T_R : \mathbb{R}^2 \longrightarrow \mathbb{R}^2$ captures all the