

last time : solved  $y^\Delta = y$ ,  $y(0) = 1$  for a general time scale.

today we want to solve  $y^\Delta = p(t)y$ ,  $y(t_0) = 1$

consider the (more general) dynamic IVP given by

$$(J) \begin{cases} y^\Delta = p(t)y & , t \in \mathbb{T}^k \\ y(t_0) = 1 \end{cases}$$

where  $p: \mathbb{T} \rightarrow \mathbb{R}$ ,  $t_0 \in \mathbb{T}$

If  $p \in C_{rd}$  and  $1 + \mu(t)p(t) \neq 0 \quad \forall t \in \mathbb{T}^k$

then the unique solution to (J) is defined by:

$e_p(t, t_0)$  which is called "the generalised exponential function on  $\mathbb{T}$ "

We can also write  $e_p(t, t_0)$  explicitly:

$$e_p(t, t_0) = \begin{cases} \exp \left[ \int_{t_0}^t \frac{1}{\mu(\tau)} \text{Log} [1 + \mu(\tau)p(\tau)] \Delta \tau \right], & \mu > 0 \\ \exp \left[ \int_{t_0}^t p(\tau) d\tau \right], & \mu = 0 \end{cases}$$

note here that Log is the principle logarithm

note that in the previous lecture, we defined  $e(t, 0)$ , we understand this to mean  $e(t, 0) = e_1(t, 0)$

def<sup>n</sup>: Define  $p: \mathbb{T} \rightarrow \mathbb{R}$  as regressive  
if  $p \in C_{rd}$  and  $1 + \mu(t)p(t) \neq 0$   
 $\forall t \in \mathbb{T}^{\kappa}$ .

The space of all regressive functions  
is denoted  $\mathcal{R}$  (funny-looking  $\mathbb{R}$ )

Some useful properties of  $e_p(t, t_0)$  are  
summarized in the following theorem:

THM (1) If  $p, q \in \mathcal{R}$ , then

$$(I) e_0(t, t_0) \equiv 1 \text{ and } e_p(t, t) = 1$$

$$(II) e_p(\sigma(t), t_0) = (1 + \mu(t)p(t)) e_p(t, t_0)$$

$$(III) e_p(t, t_0) = \frac{1}{e_p(t_0, t)}$$

$$(IV) e_p(t, t_0) e_p(t_0, r) = e_p(t, r)$$

$$(V) \left( \frac{1}{e_p(t, t_0)} \right)^{\Delta} = \frac{-p(t)}{e_p^{\sigma}(t, t_0)}$$

where  $e_p^{\sigma}(t, t_0) = e_p(\sigma(t), t_0)$

proof (II): we know  $f^{\sigma} = f + \mu f^{\Delta}$   
so,

$$e_p(\sigma(t), t_0) = e_p(t, t_0) + \mu(t) e_p^{\sigma}(t, t_0)$$

$$= e_p(t, t_0) + \mu(t) p(t) e_p(t, t_0)$$

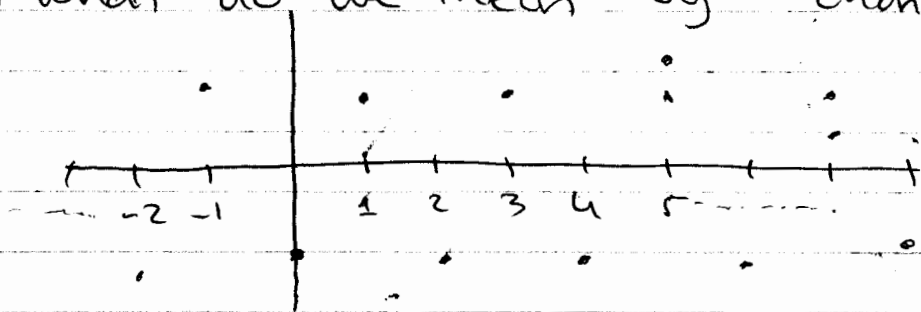
$$= (1 + \mu(t)p(t)) e_p(t, t_0)$$

example consider the IVP

$$\textcircled{E} \begin{cases} y' = ay, & t \in \mathbb{T}^k, \mathbb{T} \text{ arbitrary} \\ y(0) = 1 \end{cases} \quad \begin{matrix} a < -1 \\ a = \text{constant} \end{matrix}$$

for  $\mathbb{T} = \mathbb{Z}$ , show that the solution to  $\textcircled{E}$  changes sign at every point in  $\mathbb{Z}$ .

\*what do we mean by 'changes sign'?



well, a solution,  $y$ , to  $\textcircled{E}$  ( $\mathbb{T} = \mathbb{Z}$ ) changes sign when  $y(t) y(\sigma(t)) < 0$ .

Here,  $p(t) \equiv a$ ,  $t_0 = 0$

so our solution:

$$y(t) = e_p(t, t_0) = e_a(t, 0)$$

and

$$y(\sigma(t)) = e_p(\sigma(t), t_0)$$

$$= e_a(\sigma(t), 0)$$

$$= (1 + \mu(t)a) e_a(t, 0)$$

by THM ① (ii)

$$\text{so, } y(t) y(\sigma(t)) = e_a(t, 0) e_a(\sigma(t), 0)$$

$$= e_a(t, 0) (1 + \mu(t)a) e_a(t, 0)$$

$$= [e_a(t, 0)]^2 (1 + \mu(t)a)$$

$$= [e_a(t, 0)]^2 (1 + a)$$

$$(\mu = 1, \mathbb{T} = \mathbb{Z})$$

$< 0$  when  $a < -1$

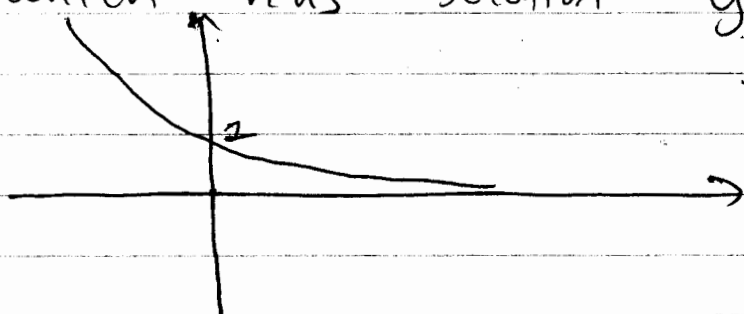
for general  $\mathbb{T}$ , we need  $|1 + \mu(t)a| < 0$   
for our solutions to "oscillate".

lets compare our sol<sup>n</sup>'s to IVP using  
 $\mathbb{T} = \mathbb{Z}$  and  $\mathbb{T} = \mathbb{R}$ : We already have  
 $\mathbb{T} = \mathbb{Z}$ . For  $\mathbb{T} = \mathbb{R}$ ,

$$y' = ay, \quad a < -1$$

$$y(0) = 1$$

which has solution  $y = e^{at}$



\* so our "general" exponential in  $\mathbb{Z}$   
is oscillatory

examples of  $e_p(t, t_0)$

$$(i) \quad \mathbb{T} = h\mathbb{Z}, \quad h > 0 \quad p(t) = \alpha \in \mathbb{R} \\ = \text{constant.}$$

then,

$$e_\alpha(t, 0) = (1 + \alpha h)^{\frac{t}{h}}$$

To verify this, we show  $y(t) = e_\alpha(t, 0)$   
satisfies:

$$y^\Delta = \frac{y(t+h) - y(t)}{h}$$

$$= \alpha y(t) = p(t)y(t)$$

and that  $y(0) = 1$ .

Consider initial condition first:

$$y(0) = e_x(0,0) = (1+\alpha h)^0 = 1$$

$$y^\Delta(t) = \frac{y(t+h) - y(t)}{h} = \frac{(1+\alpha h)^{\frac{t+h}{h}} - (1+\alpha h)^{\frac{t}{h}}}{h}$$

$$= \frac{(1+\alpha h)^{\frac{t}{h}} (1+\alpha h) - (1+\alpha h)^{\frac{t}{h}}}{h}$$

$$= (1+\alpha h)^{\frac{t}{h}} \left( \frac{1+\alpha h - 1}{h} \right)$$

$$= \alpha (1+\alpha h)^{\frac{t}{h}} = \alpha y(t)$$

as required.